NAG Fortran Library Routine Document

S17AKF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

S17AKF returns a value for the derivative of the Airy function Bi(x), via the routine name.

2 Specification

real FUNCTION S17AKF(X, IFAIL)
INTEGER IFAIL
real X

3 Description

This routine calculates an approximate value for the derivative of the Airy function Bi(x). It is based on a number of Chebyshev expansions.

For x < -5,

$$\operatorname{Bi}'(x) = \sqrt[4]{-x} \left[-a(t)\sin z + \frac{b(t)}{\zeta}\cos z \right],$$

where $z = \frac{\pi}{4} + \zeta$, $\zeta = \frac{2}{3}\sqrt{-x^3}$ and a(t) and b(t) are expansions in the variable $t = -2\left(\frac{5}{x}\right)^3 - 1$. For $-5 \le x \le 0$,

$$Bi'(x) = \sqrt{3}(x^2 f(t) + g(t)),$$

where f and g are expansions in $t = -2\left(\frac{x}{5}\right)^3 - 1$.

For 0 < x < 4.5,

$$\operatorname{Bi}'(x) = e^{3x/2}y(t),$$

where y(t) is an expansion in t = 4x/9 - 1. For 4.5 $\leq x < 9$,

$$\operatorname{Bi}'(x) = e^{21x/8}u(t),$$

where u(t) is an expansion in t = 4x/9 - 3. For $x \ge 9$,

Bi'(x) =
$$\sqrt[4]{x}e^{z}v(t)$$
,
where $z = \frac{2}{3}\sqrt{x^{3}}$ and $v(t)$ is an expansion in $t = 2\left(\frac{18}{z}\right) - 1$

For |x| < the square of the *machine precision*, the result is set directly to Bi'(0). This saves time and avoids possible underflows in calculation.

For large negative arguments, it becomes impossible to calculate a result for the oscillating function with any accuracy so the routine must fail. This occurs for $x < -\left(\frac{\sqrt{\pi}}{\epsilon}\right)^{4/7}$, where ϵ is the *machine precision*.

For large positive arguments, where Bi' grows in an essentially exponential manner, there is a danger of overflow so the routine must fail.

4 References

Abramowitz M and Stegun I A (1972) Handbook of Mathematical Functions (3rd Edition) Dover Publications

5 Parameters

1: X – *real*

On entry: the argument x of the function.

2: IFAIL – INTEGER

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

X is too large and positive. On soft failure the routine returns zero.

IFAIL = 2

X is too large and negative. On soft failure the routine returns zero.

7 Accuracy

For negative arguments the function is oscillatory and hence absolute error is appropriate. In the positive region the function has essentially exponential behaviour and hence relative error is needed. The absolute error, E, and the relative error ϵ , are related in principle to the relative error in the argument δ , by

$$E \simeq |x^2 \operatorname{Bi}(x)| \delta \quad \epsilon \simeq \left| \frac{x^2 \operatorname{Bi}(x)}{\operatorname{Bi}'(x)} \right| \delta.$$

In practice, approximate equality is the best that can be expected. When δ , ϵ or E is of the order of the *machine precision*, the errors in the result will be somewhat larger.

For small x, positive or negative, errors are strongly attenuated by the function and hence will effectively be bounded by the *machine precision*.

For moderate to large negative x, the error is, like the function, oscillatory. However, the amplitude of the absolute error grows like $\frac{|x|^{7/4}}{\sqrt{\pi}}$. Therefore it becomes impossible to calculate the function with any accuracy if $|x|^{7/4} > \frac{\sqrt{\pi}}{\delta}$.

Input

Input/Output

For large positive x, the relative error amplification is considerable: $\frac{\epsilon}{\delta} \sim \sqrt{x^3}$. However, very large arguments are not possible due to the danger of overflow. Thus in practice the actual amplification that occurs is limited.

8 Further Comments

None.

9 Example

The example program reads values of the argument x from a file, evaluates the function at each value of x and prints the results.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*
      S17AKF Example Program Text
*
      Mark 14 Revised. NAG Copyright 1989.
*
      .. Parameters ..
                        NIN, NOUT
      INTEGER
      PARAMETER
                        (NIN=5,NOUT=6)
      .. Local Scalars ..
*
                        Х, Ү
      real
      INTEGER
                        IFAIL
      .. External Functions ..
      real
                       S17AKF
      EXTERNAL
                        S17AKF
      .. Executable Statements ..
4
      WRITE (NOUT, *) 'S17AKF Example Program Results'
      Skip heading in data file
4
      READ (NIN, *)
      WRITE (NOUT, *)
      WRITE (NOUT, *) '
                                         Y
                                                   IFAIL'
                            Х
      WRITE (NOUT, *)
   20 READ (NIN, *, END=40) X
      IFAIL = 1
*
      Y = S17AKF(X, IFAIL)
*
      WRITE (NOUT, 99999) X, Y, IFAIL
      GO TO 20
   40 STOP
99999 FORMAT (1X, 1P, 2e12.3, I7)
      END
```

9.2 Program Data

S17AKF Example Program Data -10.0 -1.0 0.0 1.0 5.0 10.0 20.0

9.3 Program Results

S17AKF Example Program Results

Х	Y	IFAIL
-1.000E+01 -1.000E+00 0.000E+00 1.000E+00 5.000E+00 1.000E+01 2.000E+01	1.194E-01 5.924E-01 4.483E-01 9.324E-01 1.436E+03 1.429E+09 9.382E+25	0 0 0 0 0 0